We Claim:

1. A method of continuously specifying the mudweight to be used in a drilling operation, comprising the steps of:

    (a)   generating a source signal from a bottom hole assembly;

    (b)   detecting at least one receiver signal using said bottom hole assembly;

    (c)   computing a frequency dependent characteristic of said at least one receiver signal;

    (d)   using said frequency dependent characteristic to estimate a property of a formation in the region of said bottom hole assembly; and

    (e)   using said frequency dependent characteristic to specify said mudweight.

2. The method of claim 2 wherein said bottom hole assembly comprises a drilling apparatus.

3. The method of claim 2 wherein said source signal is a noise spectrum generated by a drill bit of said drilling apparatus.

4. The method of claim 3 wherein said step of determining frequency dependence is carried out by cross-correlation analysis.

5. The method of claim 4 wherein said receiver signal comprises a direct formation signal, and wherein said formation surrounds said borehole.

6. The method of claim 4 wherein said receiver signal comprises a reflected signal, and wherein said formation is ahead of said borehole.

7. The method of claim 1 wherein said frequency dependent characteristic is amplitude attenuation.

8. The method of claim 7 wherein said formation property is pore pressure.

9. The method of claim 8 wherein said pore pressure is estimated from a frequency dependent attenuation relationship.

10. The method of claim 1 wherein said frequency dependent characteristic is wave propagation velocity.

11. The method of claim 10 wherein said formation property is pore pressure.

12. The method of claim 1 wherein said source signal is generated by an active source located on said bottom hole assembly.

13. The method of claim 12 wherein said step of determining frequency dependence is carried out by a frequency component analysis.

14. The method of claim 1 wherein said receiver signal comprises a direct borehole signal.

15. The method of claim 14 wherein said formation property is permeability.

16. A method of continuously estimating the pore pressures of formations ahead of a bottom hole assembly, comprising the steps of

    a) generating a source signal from said bottom hole assembly;

    b) detecting at least one receiver signal using said bottom hole assembly;

    c) using said source signal and said at least one receiver signal to estimate a pore pressure of at least one said formation; and

    d) repeating steps a), b), and c) as said bottom hole assembly moves sequentially downward through said formations.

17. A method of continuously monitoring the wellbore pressure safety margin corresponding to formations ahead of a bottom hole assembly, comprising the steps of

    a) generating a source signal from said bottom hole assembly;

    b) detecting at least one receiver signal using said bottom hole assembly;

    c) using said source signal and said receiver signal to determine a pore pressure of said formation;

d) using said pore pressure to monitor said wellbore pressure safety margin; and

e) repeating steps a), b), c) and d) as said bottom hole assembly moves sequentially downward through said formations.

18. A method of continuously optimizing the weight of drilling mud used in a drilling operation, comprising the steps of

a) generating a source signal from a bottom hole assembly;

b) detecting at least one receiver signal using said bottom hole assembly;

c) using said source signal and said at least one receiver signal to determine a pore pressure of a formation ahead of said bottom hole assembly; and

d) using said pore pressure to specify a weight of said drilling mud which corresponds to a target wellbore pressure safety margin.

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